MULTI-SPEED CHART DRIVE

Model EUA-20-26

SERVICE INFORMATION

The following Heath Company services are available if you need them: Replacement Parts, Technical Consultation, and Factory Service. Address all correspondence to:

HEATH COMPANY
Benton Harbor, Michigan 49022

For prompt service, use a separate letter for each department you write to.

REPLACEMENT PARTS

If a replacement part is needed, please include the following information in your letter:

1. Part number and description.
2. Model Number and Series Number of the equipment.

If your equipment is in the Warranty period, add:

3. Date of purchase.
4. Nature of defect.

Heath Company will fill your order promptly. Please DO NOT RETURN PARTS unless they are requested. Parts that are damaged through carelessness or misuse by the customer will not be replaced without cost.

TECHNICAL CONSULTATION

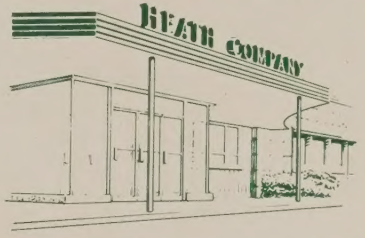
You can write to our Technical Consultants for help with any Heath equipment, or for answers to any questions about the use of this equipment.

The completeness and accuracy of the advice mailed back to you depends entirely on the information in your letter. Be sure to include:

1. The Model Number and Series Number of the equipment (on blue and white identification label).
2. Date of purchase.
3. An exact description of the difficulty. Include switch positions, connections to other units, operating procedures, voltage reading, and any other information you think might be helpful.
4. List everything you have done in attempting to correct the difficulty.

FACTORY REPAIR SERVICE

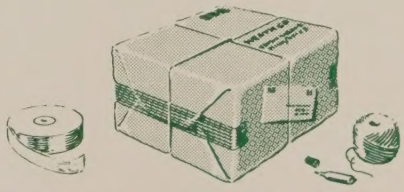
You can return your equipment to the Heath Company Service Department to have it repaired for a minimum service fee. (Equipment that has been modified will not be accepted for repair.) Refer to Shipping Instructions for details on how to package and ship the equipment.



To be eligible for replacement parts under the terms of the Warranty, equipment returned for Factory Repair Service must be accompanied by the invoice or the sales slip, or a copy of either. (If you send the original invoice or sales slip, it will be returned to you.)

SHIPPING INSTRUCTIONS

Check the equipment to see that all parts and screws are in place. Then, wrap the equipment in heavy paper. Place the equipment in a strong carton, and put at least three inches of resilient packing material (shredded paper, excelsior, etc.) on all sides, between the equipment and the carton.



Seal the carton with gummed paper tape and tie it with a strong cord. Ship it by prepaid Express or insured Parcel Post to:

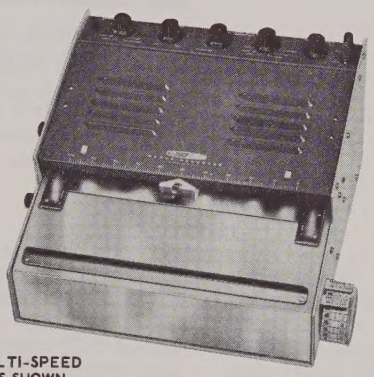
HEATH COMPANY
Benton Harbor, Michigan 49022

Attach a letter containing the following information, to the outside of the carton:

1. Your name and return address.
2. Date of purchase.
3. A brief description of the difficulty.
4. Your authorization to ship the repaired unit back to you C.O.D. for the service and shipping charges, plus the cost of parts not covered by the Warranty.

INSTALLATION AND OPERATION
OF THE HEATH
MULTI-SPEED CHART DRIVE

MODEL EUA-20-26



NOTE: THE MULTI-SPEED CHART DRIVE IS SHOWN INSTALLED IN THE HEATH SERVO RECORDER.

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HEATH COMPANY
BENTON HARBOR, MICHIGAN

595-808

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SPECIFICATIONS

Chart Speeds	5 seconds to 2 hours per inch in 21 speeds when using the internal chart drive signal. See Figure 14 on Page 13. Any chart speed up to 5 seconds per inch when using an external chart drive signal.
Chart Advancement Steps	600 steps per inch; 2 steps per cycle of the signal applied to the motor drive circuit. The motor will accurately step from 0 to 40 cps, and will run accurately at 60 cps.
External Signal Input	Input terminals for external chart drive signals. See External Drive Signals on Page 14. Input terminals for synchronization signals from other Multi-Speed Chart Drives or from other events.
Auxiliary Output Signal	Approximately 4 volts peak-to-peak square wave with 20 microseconds rise time and .2 microsecond fall time.
Auxiliary Output Impedance	68 Ω.
Transistor Complement	27 - 2N3393: Schmitt trigger, binaries, and emitter follower. 2 - 2N3416: Motor drive.
Diode Complement	29 - 1N191 crystal diode: Twenty-four binary, and five feedback diodes. 1 - 1N751 zener diode: DC level adjuster. 2 - 750 ma 100 V PIV silicon diodes: Power supply rectifiers.
Controls	21-position Chart Speed switch. External-Internal signal switch.
Power Requirements	105-125 volts AC, 60 cps, 30 watts.
Dimensions (circuit board only)	9-1/2" wide x 3-1/4" high x 1" deep.
Net Weight	3 lbs.

EXTERNAL SIGNAL CONSIDERATIONS

Sine Wave	15 cps to 10 kc, with a minimum voltage as shown in Figure 15 on Page 15.
Square Wave	0 to 10 kc, with a minimum of 3 volts peak-to-peak and maximum rise and fall times of 20 microseconds.

Pulses. . . . . 0 to 10,000 pulses per second, with a minimum amplitude dependent upon the pulse duration time.

External Signal Frequency. . . . . To obtain a chart speed other than the 21 switch-selected speeds, the required external signal frequency is calculated as follows:

$$\text{External Signal Frequency} = \frac{60 \text{ X Chart Speed switch setting (SEC/IN.)}}{\text{Desired Chart Speed (SEC/IN.)}}$$

IMPORTANT: When using external signals above 60 cps, the Chart Speed switch should be set to divide the signal down to 60 cps or less. This limits the maximum chart speed to 5 seconds per inch and keeps it from exceeding the chart motor rating.

INTRODUCTION

The Multi-Speed Chart Drive provides twenty-one accurate chart speeds that are selected with the Chart Speed switch on your Heath Servo Recorder. All of the most-used chart speeds from 12 inches per minute to 1/2 inch per hour (also stated as 5 to 7200 seconds per inch) are available with this switch. The chart speeds are marked as follows on a large easy-to-read dial: seconds per inch, minutes per inch, hours per inch, inches per minute, and inches per hour.

The Chart Drive is driven by the 60 cps AC line signal. All chart speeds have the same accuracy as the frequency of this AC line signal. Since the motor drive operates on a stepping principle, the chart is advanced in a precise step for each half cycle of the chart drive signal that is applied to the motor coil. These steps of chart movement are so small (.001667 inches per half cycle) that they cannot be seen as individual steps. The chart moves one inch for every 600 half cycles of chart drive signal.

One of the reasons for using a stepping motor to drive the chart is that it allows binary division techniques to be used. These techniques, which are normally found in digital computers, are used to provide lower chart speeds that have the same accuracy as the frequency of the chart drive signal. Therefore, a wide range of chart speeds can be selected electronically by the Chart Speed switch, without the time lag and backlash problems that occur when mechanical gear trains are changed.

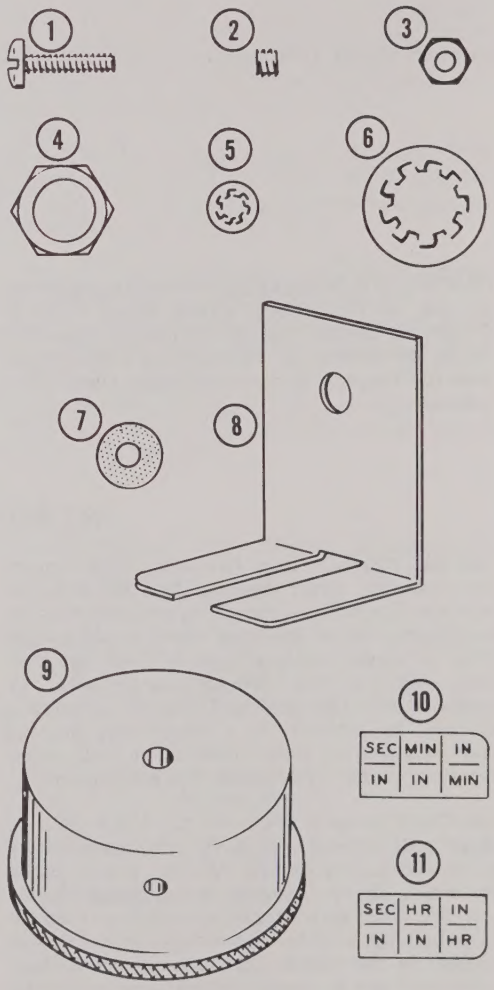
Another feature of the Multi-Speed Chart Drive is that it can also be driven by an external signal to provide an unlimited number of chart speeds below 12" per minute. The chart speed can be programmed by changing the frequency of the external signal according to some time sequence. The chart speed can also be synchronized with other events, or with other Heath Servo Recorders that have the Multi-Speed Chart Drive installed, by using the signal available at the auxiliary output jack.

This Multi-Speed Chart Drive unit is designed for installation in the Heath EUW-20A Servo Recorder and the EUW-301 Recording ph Meter. Check each part against the following Parts List and complete the steps in the Installation section of this Manual. Or if you have purchased the Heath Model EUW-20M Servo Recorder or EUW-301M Recording pH Meter, omit the Parts List and Installation sections, as this Chart Drive is completely installed and ready to operate in the Servo Recorder and pH Meter.

PARTS LIST

The numbers in parentheses are keyed to the numbers on the Parts Pictorial.

PART No.	PARTS Per Kit	DESCRIPTION
HARDWARE		
(1) 250-162	4	6-32 x 1/2" screw
(2) 250-105	1	8-32 x 1/8" setscrew
(3) 252-3	3	6-32 nut
(4) 252-7	1	Control nut
(5) 254-1	3	#6 lockwasher
(6) 254-4	2	Control lockwasher
(7) 253-35	3	Fiber washer
MISCELLANEOUS		
(8) 204-M708F	1	Speed switch bracket
(9) 462-226	1	Speed switch knob
(10) 390-153	2	Rear label (1 extra)
(11) 390-154	2	Front label (1 extra)
390-167	2	Speed switch label (1 extra)
	1	Multi-speed chart drive assembly
595-808	1	Manual



INSTALLATION

In the following steps, the Multi-Speed Chart Drive will be installed in place of the chart motor in your Heath Model EUW-20A Servo Recorder.

Check each step off in the space provided (✓) . This will keep you from losing your place while performing the step.

( ) Set the Servo Recorder on its back and remove the chart paper guide plate as shown in Figure 1. Save the three screws to install this plate in a later step.

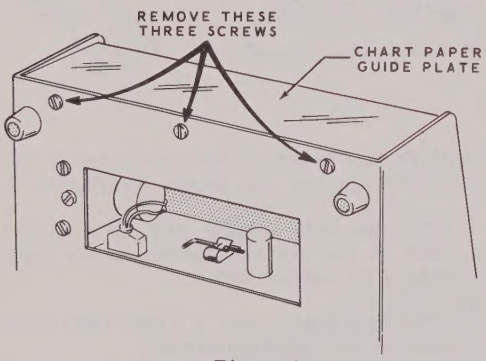


Figure 1

( ) Refer to Figure 2 and remove the chart motor from the Recorder as follows: unplug the AC plug; remove the three mounting screws with washers; then remove the motor. Save the screws and washers to mount the new motor later.

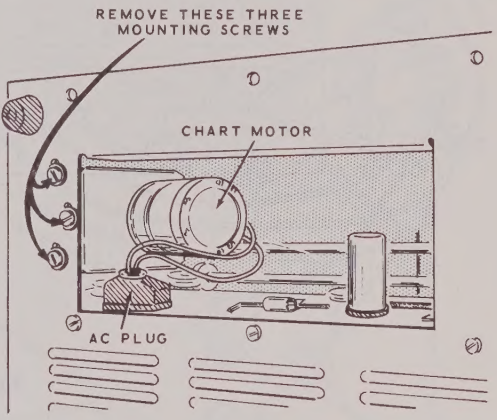


Figure 2

NOTE: Be careful when handling the Multi-Speed Chart Drive assembly during installation, so the interconnecting wires do not break loose. If any of the wires are disconnected when this assembly is received, refer to Figures 3 and 4 (on Page 6) and reconnect these wires at the locations shown.

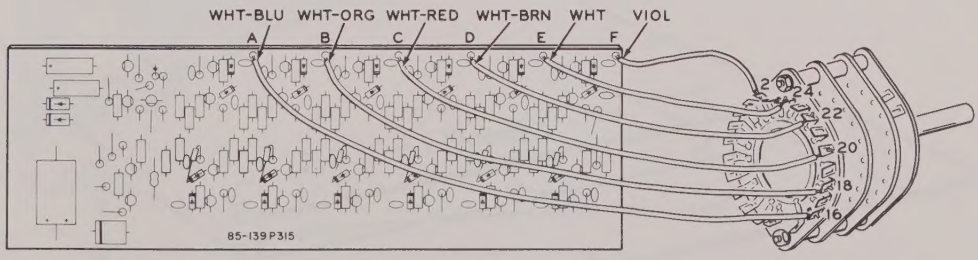


Figure 3

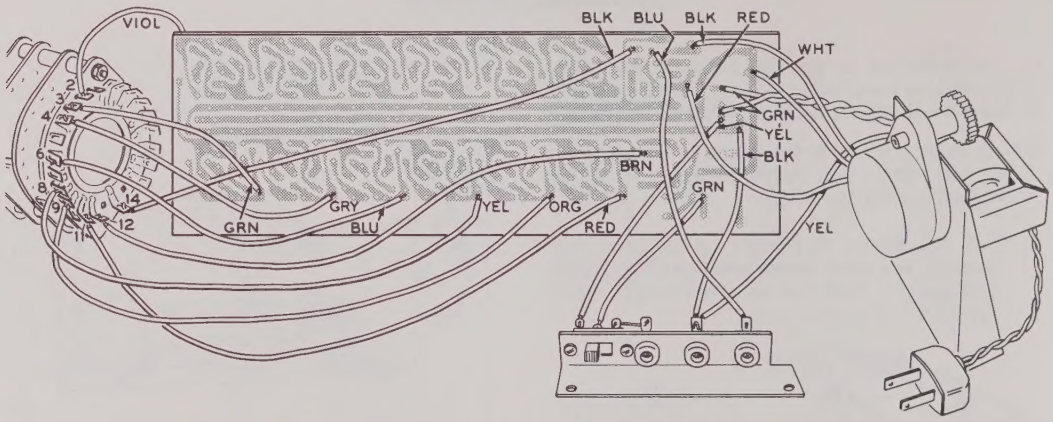


Figure 4

NOTE: The later production models of the EUW-20A Servo Recorders have been prepared at the factory with predrilled mounting holes with a plug button installed. If your Recorder has a plug button installed on the right side of the cabinet bottom (location shown in Figure 5), remove the button and omit the next three steps.

( ) Mark the locations for five holes in the cabinet bottom as shown in Figure 5.

( ) Drill one hole using a 3/8" or a 25/64" drill at the marked location on the right side of the cabinet bottom.

( ) Drill four holes using a 5/32" (#22) drill at the other marked locations.

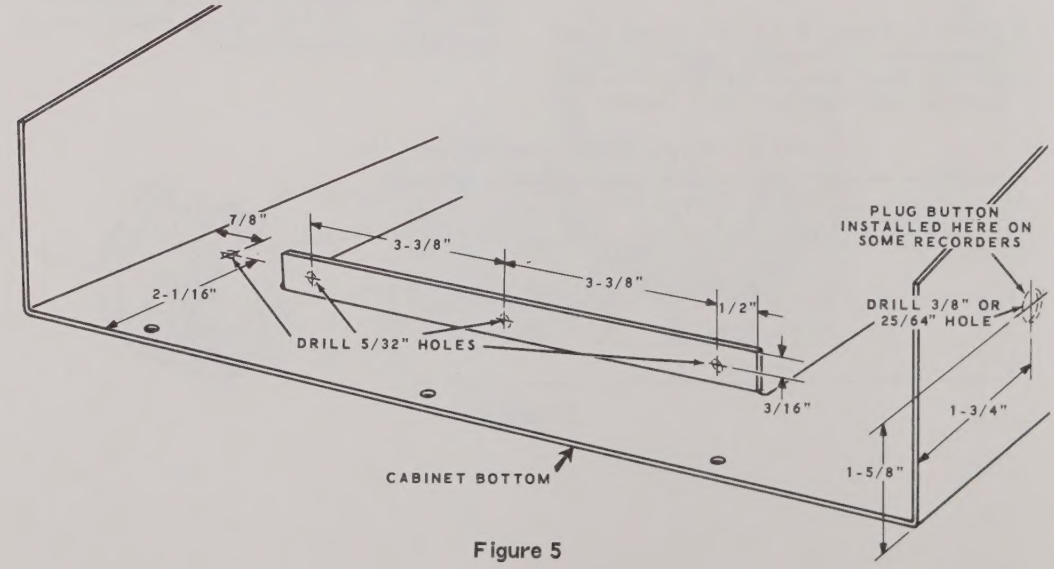


Figure 5

( ) Place a control lockwasher on the speed switch shaft; then insert the switch shaft through the hole at the side of the cabinet. See Figure 6. The speed switch will be fastened later.

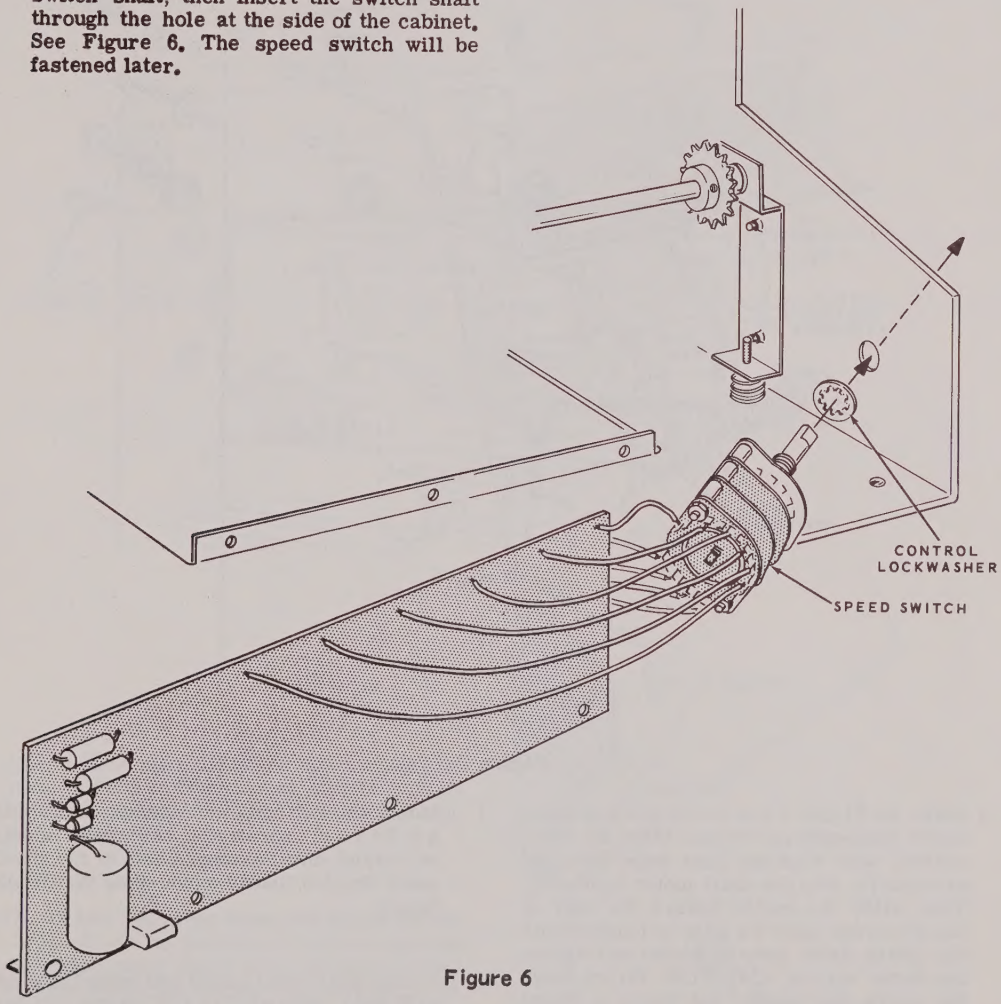


Figure 6

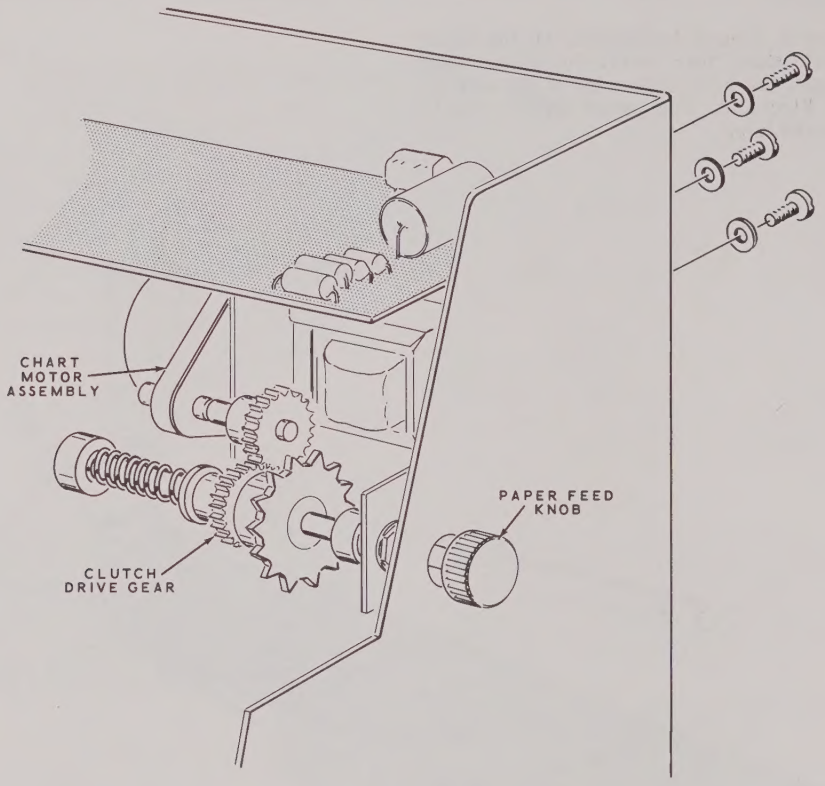


Figure 7

( ) Refer to Figure 7 and mount the new chart motor assembly as follows: Start the three screws with washers (that were removed previously) into the chart motor assembly. Then slide the motor toward the rear of the Recorder until its gear is meshed with the clutch drive gear as shown and tighten the three screws. CAUTION: Do not mesh the gears too tightly but leave a small amount of backlash between them or the chart motor will not operate.

Refer to Figure 8 for the following steps.

NOTE: The circuit board and the switch bracket will be fastened to the cabinet bottom in the following steps. Do not tighten any of the screws until all four screws are in place.

( ) Mount the left end of the circuit board with a 6-32 x 1/2" screw at A. This screw should be turned into the tapped hole of the small angle bracket that is mounted on the circuit board.

( ) Fasten the circuit board and switch bracket at B and C with a 6-32 x 1/2" screw, a fiber washer, a #6 lockwasher, and a 6-32 nut at each location. Place the fiber washers between the circuit board and cabinet flange, and position the bracket as shown.

( ) Fasten the right end of the circuit board at D with a 6-32 x 1/2" screw, a fiber washer, a #6 lockwasher, and a 6-32 nut.

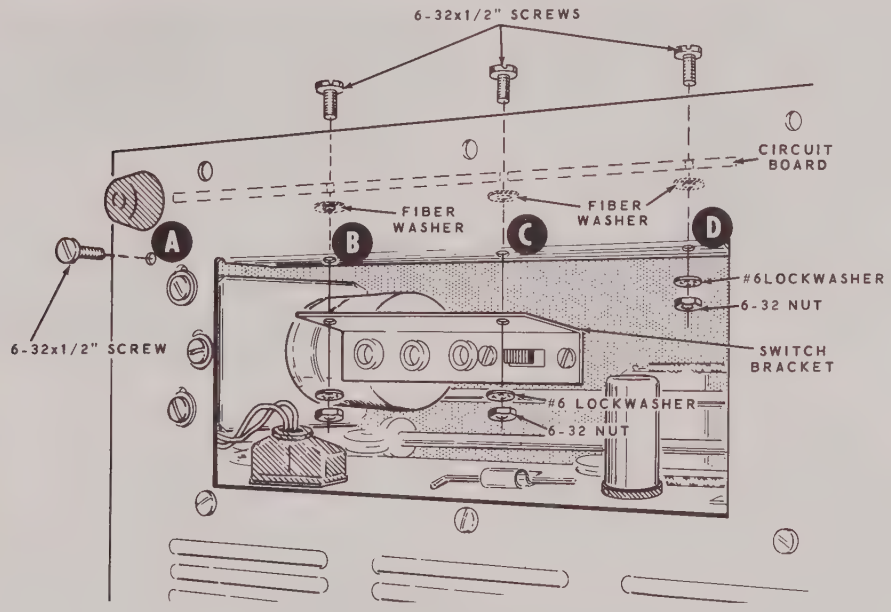


Figure 8

( ) Check to be sure the wires are not pinched between the cabinet bottom and the chart drive assembly. Then tighten the screws at A, B, C, and D.

NOTE: In the following steps, the Speed switch and bracket can be positioned so you can read the indicated chart speed from the top or front of the Recorder. Determine the position from which you plan to read the chart speeds before fastening the switch and bracket.

( ) Install the speed switch bracket on the Speed switch with a control lockwasher and a control nut as shown in Figure 9. Do not tighten the control nut.

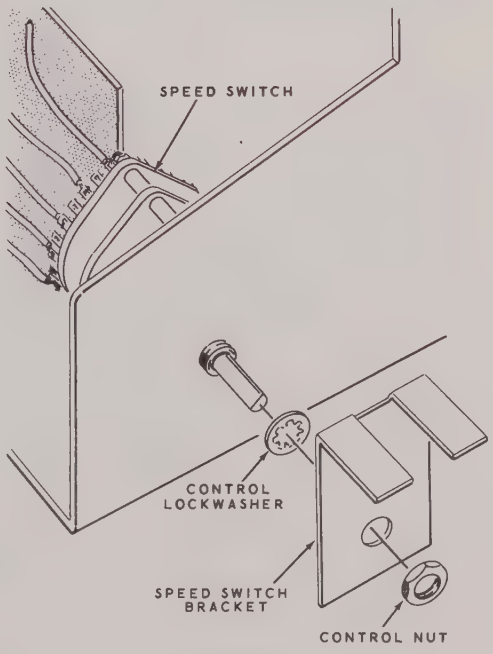


Figure 9

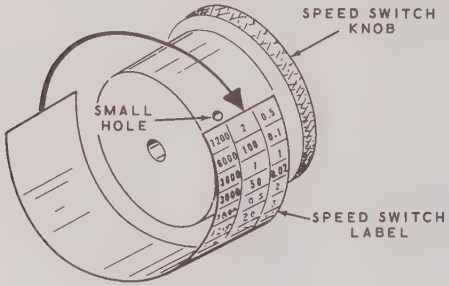


Figure 10

( ) Refer to Figure 10 and install the speed switch label on the speed switch knob as follows: remove the backing paper; position the end of the label with the number 7200 next to the small hole; and press the label in position around the knob.

( ) Use a sharp knife to cut out the blank part of the label that covers the small hole in the knob.

Refer to Figure 11 for the following steps.

( ) Install the knob on the Speed switch with an 8-32 x 1/8" setscrew. Use the allen wrench (inserted in clip near chart motor) supplied with the Servo Recorder. Position the knob with the setscrew against the flat side of the switch shaft as shown.

( ) If necessary, bend the switch bracket so it does not touch the knob or the label.

( ) While holding the Speed switch with one hand, turn the speed switch knob fully clockwise.

( ) Hold the speed switch bracket in the position where you plan to read the chart speeds; then turn the Speed switch until the numbers 5 (black) and 12 (green) at the end of the label are positioned in the window of the bracket. Remove the knob and tighten the control nut to hold the switch and bracket in the desired position.

( ) Reinstall the knob on the Speed switch. Check to be sure that the numbers 5 (black) and 12 (green) are still positioned in the window of the bracket with the knob turned fully clockwise. If necessary, reposition the switch and bracket until these numbers are positioned correctly.

( ) Locate a front label. This label is marked with black and red lettering as shown in the inset drawing on Figure 11.

( ) Install the front label on the front portion of the switch bracket as follows: Remove the backing paper, and press the label into position with the lettering facing the front of the Recorder. Also, the lettering on the front label should line up with the three rows of numbers on the speed switch label as shown in the inset drawing.

( ) Similarly install a rear label on the rear position of the switch bracket. This label is marked with black and green lettering as shown in the inset drawing on Figure 11. Position the label so its lettering lines up with the three rows of numbers on the switch label.

( ) Turn the Speed switch through all 21 positions. Check to be sure the numbers on the switch label are positioned in the window of the switch bracket at each position of the switch.

( ) Position each wire connected between the Speed switch and circuit board so the wires are separated as much as possible from each other. See Figure 11. This will prevent interaction between the binaries when operating your Recorder.

( ) Be sure the EXT-INT signal switch is in the INT position.

( ) Plug the AC plug coming from the chart motor assembly into the AC socket near the motor.

NOTE: If the chart motor does not operate when completing the following step, turn the Servo Recorder off and refer to the In Case Of Difficulty section on Page 17.

( ) Insert the line cord plug from the Servo Recorder into a 117 volt AC outlet and turn the Power switch to the Chart position. Be sure the chart motor operates.

( ) Reinstall the chart paper guide plate using the three screws removed previously.

This completes the installation of the Multi-Speed Chart Drive in your Servo Recorder.

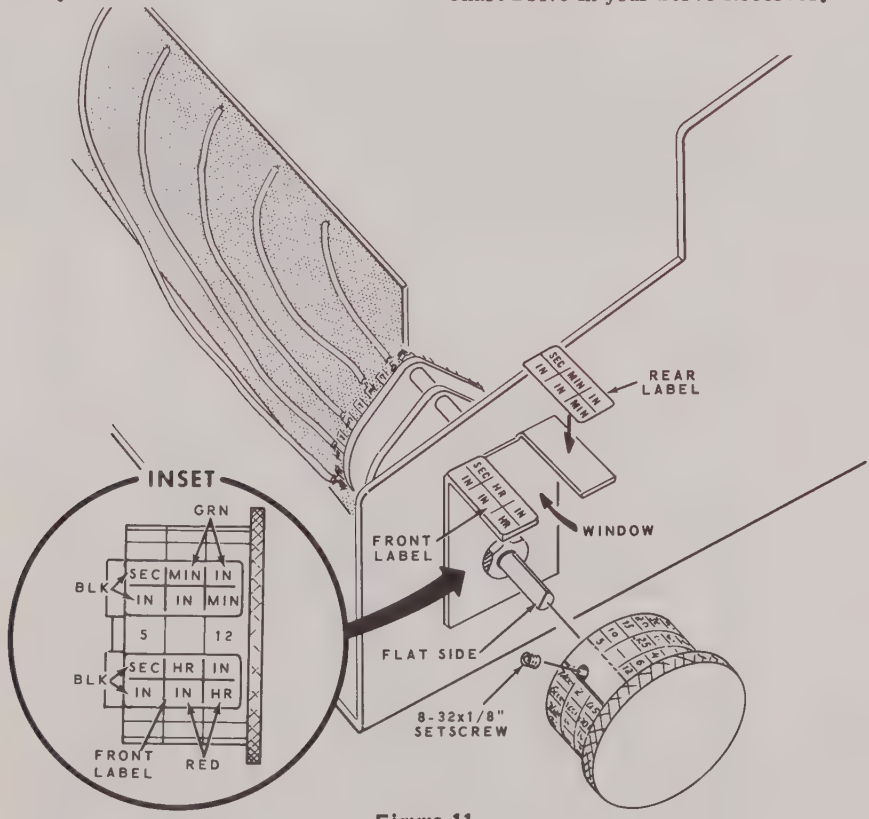


Figure 11

OPERATION

Multi-speed operation, and methods of synchronizing this Chart Drive with other events will be explained in this section. For other information about the operation of your Heath Servo Recorder, refer to your Recorder Manual.

MULTI-SPEED OPERATION

Refer to Figures 12 and 13 to locate the controls that affect the chart speed of your Recorder. Either the internal or an external drive signal can be used to drive the chart motor.

Internal Drive Signal

The EXT-INT signal switch should be set at INT to use the 60 cps internal chart drive signal. Select the desired chart speed with the 21-position Chart Speed switch. This switch is marked so you can use any of the five calibrated scales to set the chart speed. To read the chart speed, match the color of a number shown in the window with the color of the adjacent lettering on the switch bracket. See Figure 12. Example: Turn the Chart Speed switch fully counterclockwise, match the black number 7200 with the black lettering of SEC/IN to read the chart speed of 7200 SEC/IN. At the same switch position, match the red number 2 with the red lettering of HR/IN to read the same chart speed as 2 HR/IN. This same chart speed can also be read as 0.5 IN/HR.

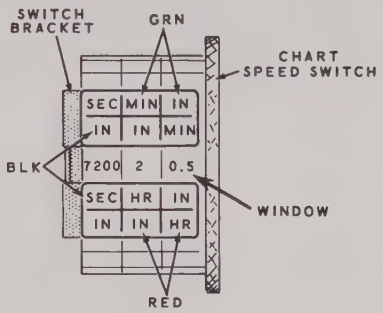


Figure 12

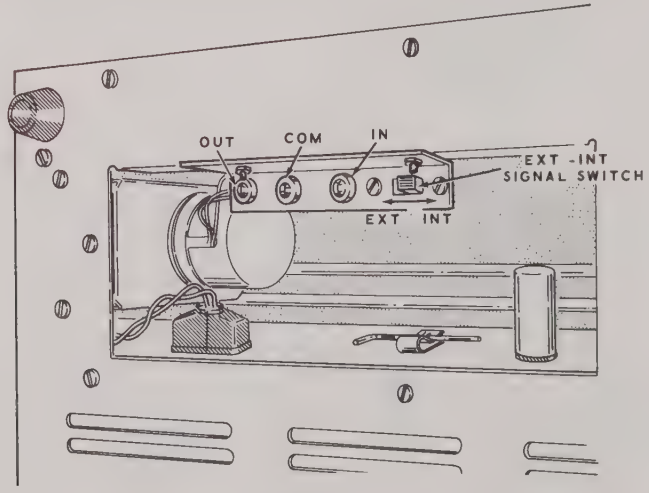


Figure 13

Note that the Chart Speed switch shows the speed in one, two, or three scales at each switch position. To read the chart speed on any scale not shown, refer to Figure 14. This Figure lists the chart speed for each of the five scales (SEC/IN; MIN/IN; IN/MIN; HR/IN; IN/HR) at all positions of the switch. Study the Figure to help determine the scale you wish to use. It is recommended that you use the SEC/IN scale because the chart speeds are marked in whole numbers for all speeds.

CHART SPEEDS

SEC/IN	MIN/IN	HR/IN	IN/MIN	IN/HR
5	.08333	.00138	12	720
10	.16667	.00277	6	360
15	.25	.00458	4	240
20	.333	.00555	3	180
30	.5	.00833	2	120
50	.83333	.01388	1.2	72
60	1	.01667	1	60
100	1.6667	.02777	.6	36
120	2	.03333	.5	30
200	3.333	.05555	.3	18
300	5	.07333	.2	12
500	8.333	.1388	.12	7.2
600	10	.1667	.1	6
900	15	.25	.0666	4
1000	16.667	.2777	.06	3.6
1200	20	.333	.05	3
1800	30	.50	.0333	2
3000	50	.8333	.02	1.2
3600	60	1	.01667	1
6000	100	1.667	.01	0.6
7200	120	2	.00833	0.5

Figure 14

External Drive Signals

Chart speeds other than those listed in Figure 14 can be selected by using an external drive signal. Speeds as fast as 5 seconds per inch as as slow as desired are possible by connecting an external drive signal in the following manner. Connect the external signal source to the IN and COM jacks as shown in Figure 13. Set the EXT-INT switch to EXT.

The external signal source can be any of the following:

1. Sine Wave - 15 cps to 10 kc with a minimum voltage as shown in Figure 15.

2. Square Wave - 0 to 10 kc with a minimum of 3 volts peak-to-peak and maximum rise and fall times of 20 microseconds.

3. Pulses - 0 to 10,000 pulses per second with a minimum amplitude dependent upon the pulse duration time.

The external drive signal should not exceed 25 volts for any type of signal.

CAUTION: Before using an external signal above 60 cps or 60 pulses per second, determine the desired chart speed and be sure to calculate the external signal frequency as given in the example that follows. Never use a chart speed faster than 5 seconds per inch, or the motor drive transistors may be damaged.

The chart speed is controlled by changing either the external signal frequency or the Chart Speed switch (or both). Chart speeds should be determined in the following manner. (Note that the chart speed can be read directly from the Chart Speed switch when the EXT-INT switch is set at INT.) With an external signal frequency of 60 cps connected to the Recorder, the chart speed can also be read directly from the switch. But when the external signal frequency is changed to other than 60 cps, the switch calibration numbers are not correct. Determine the desired chart speed; then calculate the external signal frequency with the following formula, as shown in the example.

$$\text{External Signal Frequency} = \frac{60 \times \text{Chart Speed switch setting (SEC/IN)}}{\text{Desired Chart Speed (SEC/IN)}}$$

Example: Desired Chart Speed is 18 SEC/IN. Chart Speed switch set at 120 SEC/IN.

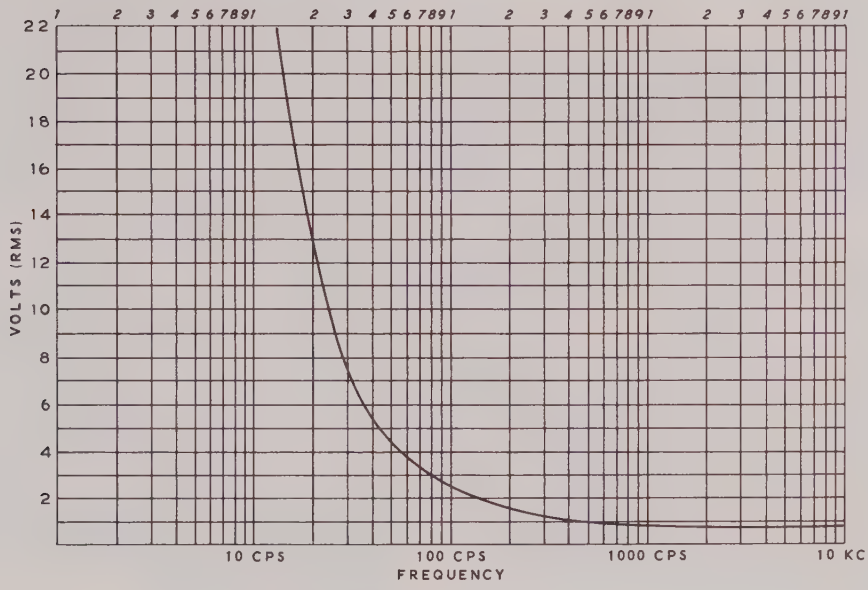
$$\text{External Signal Frequency} = \frac{60 \times 120}{18} = 400 \text{ cps.}$$

The desired chart speed in this example is 18 SEC/IN. Refer to Figure 14 and note that this chart speed cannot be selected when using the internal signal of 60 cps.

SYNCHRONIZATION

Synchronization Of Chart Drive With Other Events

The chart motor can be driven in synchronization with events that happen at certain frequencies or at individually distinct times. The synchronizing signal must come from the source of events and be connected to the IN and COM jacks, as shown in Figure 13. This signal must be within the specifications outlined previously under External Drive Signals.



MINIMUM EXTERNAL INPUT VOLTAGE (SINE WAVE)

Figure 15

Synchronization Of Other Recorders

Other Heath Servo Recorders that have the Multi-Speed Chart Drive feature can be operated in synchronization with the Chart Drive in this recorder in the following manner. NOTE: For the following explanation, Recorder #1 will supply the chart drive signal and control the chart speed of Recorder #2, so that both Recorders will operate at the same chart speed. Refer to Figure 16.

Connect a lead from the OUT jack of Recorder #1 to the IN jack of Recorder #2. Connect another lead between the COM jacks of the two Recorders.

On Recorder #1, set the EXT-INT switch to either position. This switch position depends on whether you use the internal signal or an external signal as explained under Multi-Speed Operation. If an external signal is used, connect this signal to the EXT and COM jacks.

On Recorder #2, set the EXT-INT switch at EXT, the Chart Speed switch to 5 SEC/IN, and the Power switch to the Chart position.

Now the Power switch on Recorder #1 will control both Recorders. Control the chart speed on both Recorders with the Chart Speed switch on Recorder #1. Do not change the preset position of the switches on Recorder #2 for this method of operation.

If you desire to synchronize the two Recorders with a speed ratio between the Recorders, then set the Chart Speed switch on Recorder #2 for the desired speed ratio.

Synchronization Of Other Events With The Chart Drive

The signal at the Auxiliary Output (OUT) jack can be used to synchronize other events with the Chart Drive. Connect leads from the OUT and COM jacks to the specific event to be synchronized. NOTE: The signal at the auxiliary output jack is a 4 volts peak-to-peak (approximately) square wave, with a 20 microsecond rise time, a .2 microsecond fall time, and a repetition rate of 300 cycles per inch of chart movement. The frequency available at the Auxiliary Output jack can be determined for each Chart Speed switch setting by dividing the number in the "Divide By" column on Figure 18 into the initial frequency.

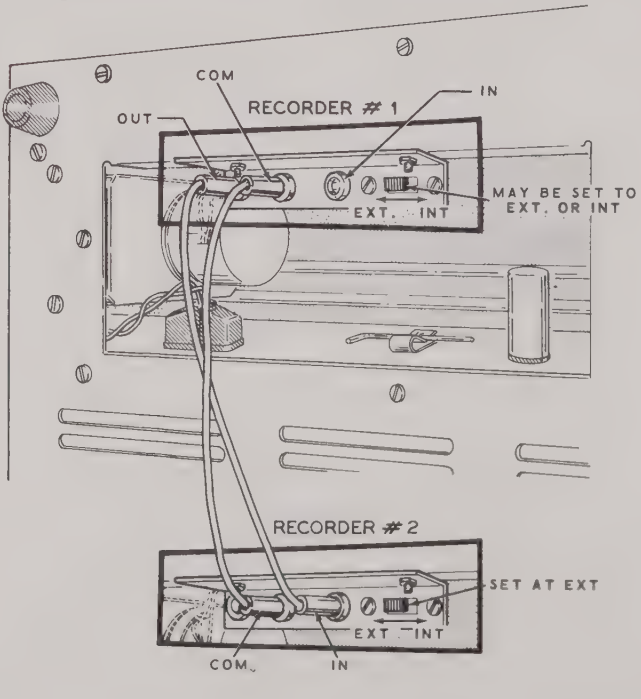


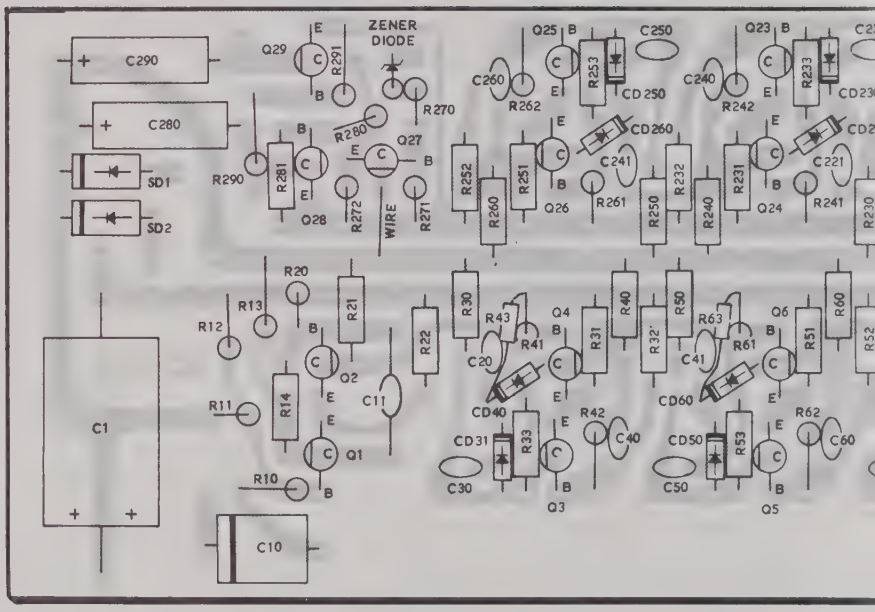
Figure 16

IN CASE OF DIFFICULTY

1. Refer to the Troubleshooting Chart to help locate the difficulty. The Circuit Board X-Ray View shows the location of the components with respect to the component side of the circuit board. The R and C numbers correspond to the R and C numbers on the Schematic.
2. If, after careful checks, the trouble is still not located and a DC oscilloscope is available, check the waveforms against those shown on the Schematic.
3. A review of the Circuit Description may be helpful in indicating where to look for the cause of the trouble.

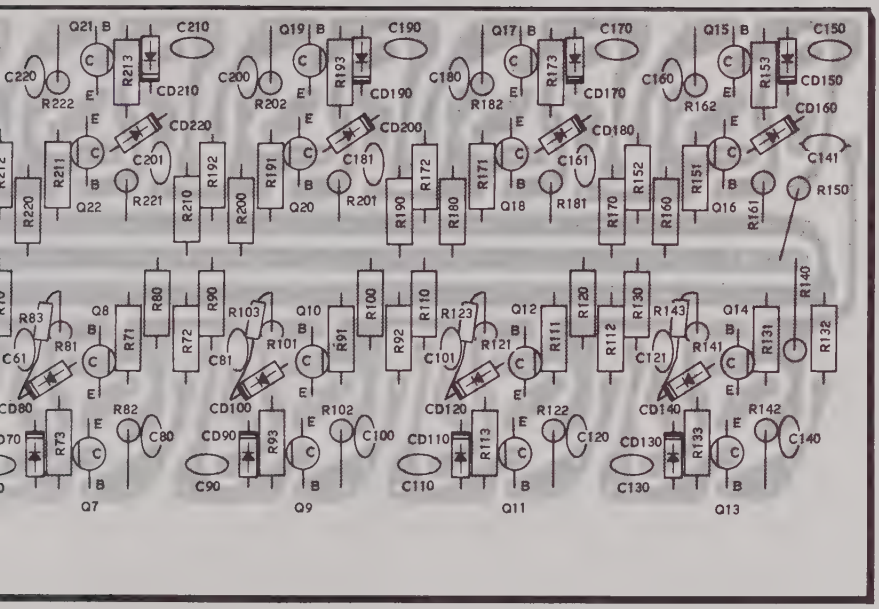
TROUBLESHOOTING CHART

TROUBLE	POSSIBLE CAUSE
Chart motor inoperative.	1. Check position of EXT-INT signal switch. 2. Be sure the AC plug from the power transformer is plugged into the AC socket of the Recorder. 3. Make sure the motor gear is not overmeshed and binding with the clutch drive gear on the Recorder. 4. Open or shorted diode SD1 or SD2. 5. Defective capacitors C1, C280, or C290. 6. Defective transistors Q1, Q2, Q27, Q28, Q29, or the associated circuit components. 7. Defective motor.
Chart speed is faster or slower than indicated on the Chart Speed switch.	1. Knob improperly positioned on shaft of Chart Speed switch. 2. Intermittent switch contacts. 3. Defective diodes CD1 through CD5, and CD31 through CD260. 4. Defective transistors Q3 through Q26 or the associated circuit components.
Chart motor operates OK on 5 SEC/IN speed, but inoperative on other speeds.	1. Defective capacitor C20, C30, or C40. 2. Defective diode CD30 or CD40. 3. Defective transistor Q3 or Q4, or the associated circuit components.



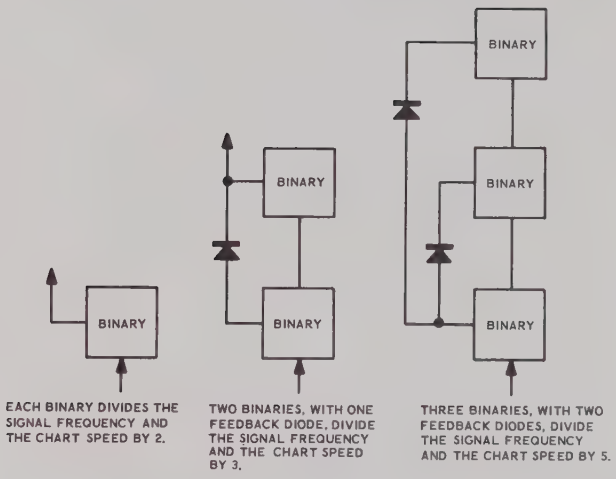
CIRCUIT BO

(VIEWED FRO



RD X-RAY VIEW

(COMPONENT SIDE)



EACH BINARY DIVIDES THE SIGNAL FREQUENCY AND THE CHART SPEED BY 2.

TWO BINARIES, WITH ONE FEEDBACK DIODE, DIVIDE THE SIGNAL FREQUENCY AND THE CHART SPEED BY 3.

THREE BINARIES, WITH TWO FEEDBACK DIODES, DIVIDE THE SIGNAL FREQUENCY AND THE CHART SPEED BY 5.

NOTES:

1. ◯ THIS SYMBOL
NUMBER ON WAFE
SHOWN ON THE SC

2. CRYSTAL DIODES
DIODES WITH THE

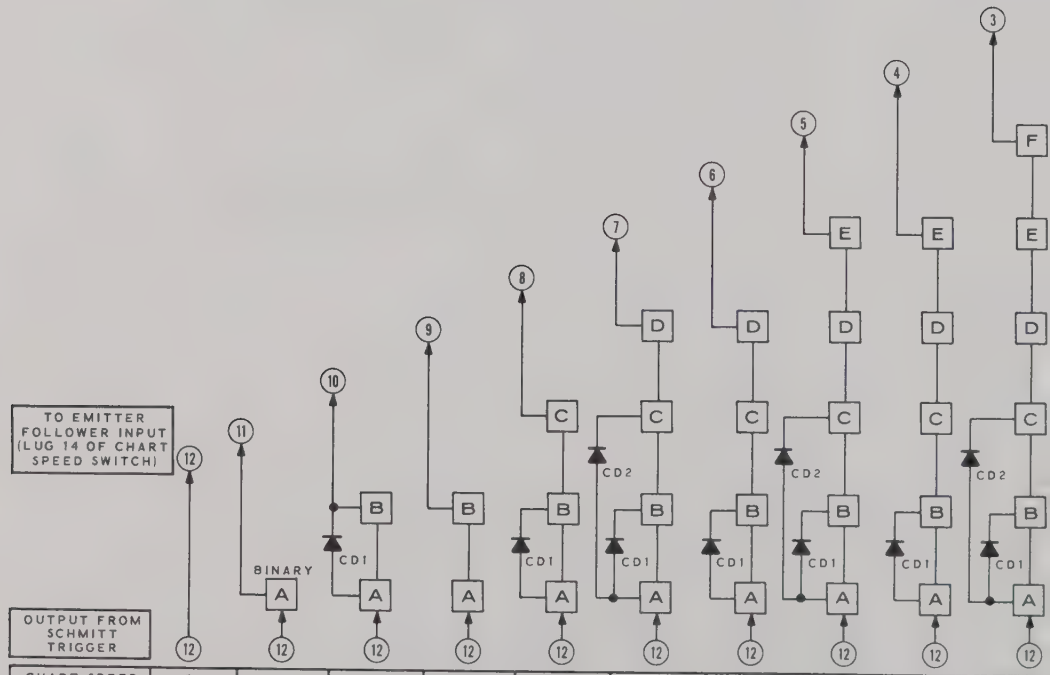
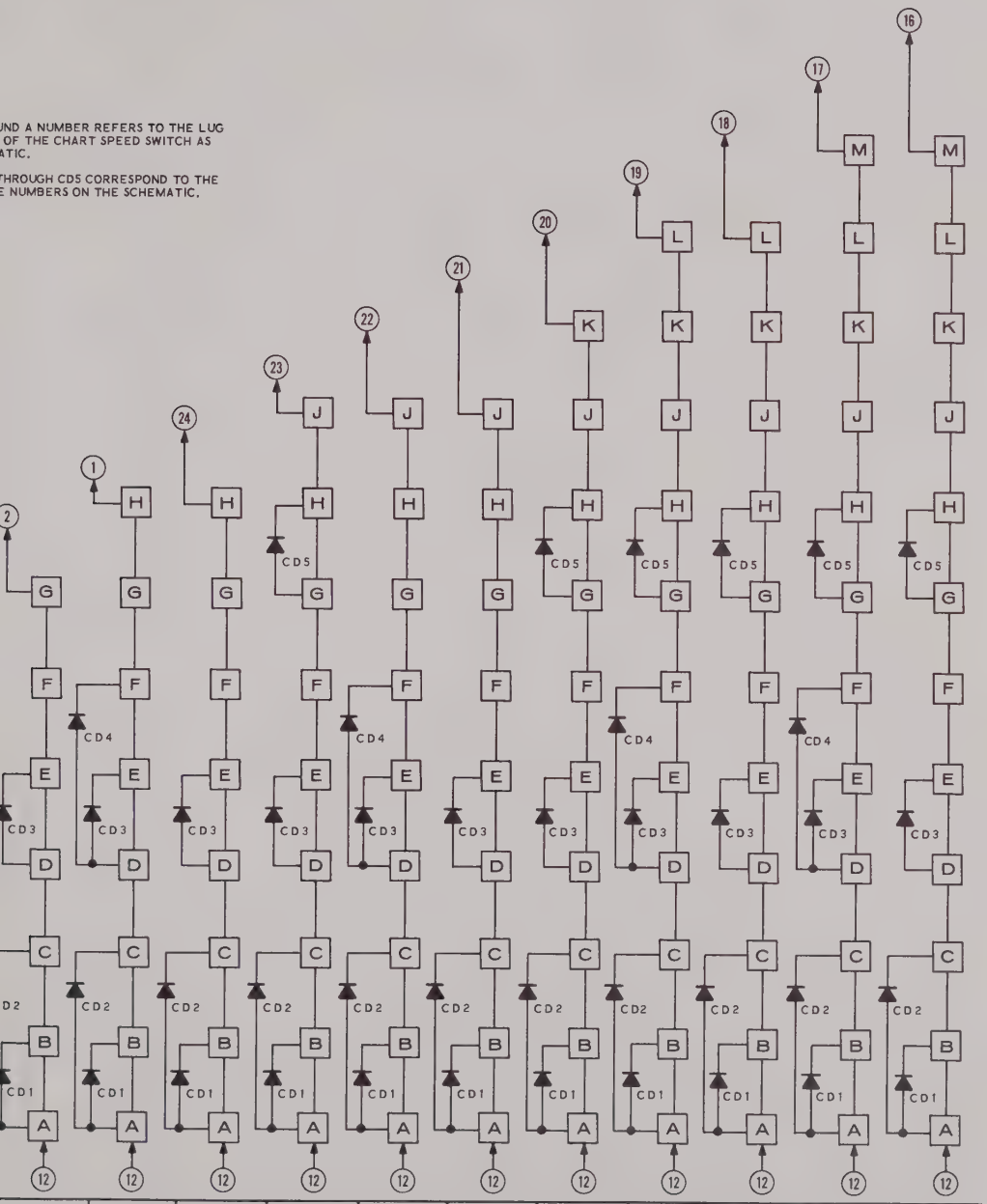


CHART SPEED IN SEC/IN	5	10	15	20	30	50	60	100	120	200
DIVIDE BY	1	2	3	4	6	10	12	20	24	40

Figure

UND A NUMBER REFERS TO THE LUG
OF THE CHART SPEED SWITCH AS
ATIC.

THROUGH CD5 CORRESPOND TO THE
E NUMBERS ON THE SCHEMATIC.



300	500	600	900	1000	1200	1800	3000	3600	6000	7200
60	100	120	180	200	240	360	600	720	1200	1440

REPLACEMENT PARTS

This list covers only those parts that may be difficult to obtain locally if replacement is required. Some of the items listed here are also listed in the Parts List on Page 4.

PART No.	DESCRIPTION
CAPACITORS	
21-21	200 μμf disc
21-36	.002 μfd disc
25-123	2 μfd 25 V electrolytic
25-111	1000 μfd 15 V electrolytic
DIODES-TRANSISTORS	
56-16	1N751 zener diode
56-26	1N191 crystal diode
57-29	750 ma 100 V PIV silicon diode
417-118	2N3393 transistor
417-94	2N3416 transistor

PART No.	DESCRIPTION
MISCELLANEOUS	
63-417	Speed switch
54-166	Power transformer
420-37	Chart motor
451-38	Chart motor gear
204-M708F	Speed switch bracket
462-226	Speed switch knob
390-153	Rear label
390-154	Front label
390-167	Speed switch label

NOTE: When the Multi-Speed Chart Drive is used with a 50 cps, AC line, replace the drive gears with the following parts so the indicated chart speeds are accurate.

451-39	Clutch drive gear in Heath Servo Recorder
451-40	Chart motor gear

CIRCUIT DESCRIPTION

Refer to the Block Diagram (Figure 17) and the Schematic (fold-out from Page 19) while reading the following Circuit Description. This description is divided into sections that correspond to the individual circuits of the Multi-Speed Chart Drive.

SCHMITT TRIGGER

A chart drive signal is coupled from Ext-Int switch S1 to the base of transistor Q1. With switch S1 at Int, a 60 cps sine wave signal is taken from the secondary of power transformer T1. With switch S1 at Ext, an external chart drive signal is taken from the In and Com jacks.

Transistor stages Q1 and Q2 form a Schmitt Trigger circuit. The output signal from this circuit is always a square wave, regardless of the type of waveform used as the input signal. The Schmitt Trigger circuit operates as follows: The positive pulse of the input signal causes Q1 to conduct, and Q2 is then cut off. When the signal goes negative, Q1 is cut off and Q2 starts conducting again. This switching occurs rapidly due to the regenerative feedback of the common emitter resistor, R22. The rapid switching action causes the signal at the collector of Q2 to be a square wave.

With the Chart Speed switch at 5 SEC/IN, the binary circuits are not used, and the signal from the collector of Q2 is connected through lugs 12 and 14 of switch wafer 3R to the input of emitter follower transistor Q27. The binary circuits will be explained later.

EMITTER FOLLOWER

Transistor stage Q27 is an emitter follower that isolates the Schmitt Trigger and the binaries from the motor drive circuit and the Auxiliary Output jack. The square wave signal coming from lug 14 of the Chart Speed switch, is coupled through the zener diode and resistor R270 to the base of Q27. The zener diode is a DC level adjuster that controls the bias voltage on the base of Q27. The signal is then coupled from the emitter of Q27 through resistor R280 to the motor drive circuit.

MOTOR DRIVE CIRCUIT

The motor drive circuit consists of transistor stages Q28 and Q29. With the positive portion of the chart drive signal applied to the base of Q28, transistor Q28 conducts and Q29 is cut off, by bias resistors R290 and R291. As the signal goes negative, the operation of Q28 and Q29 is reversed.

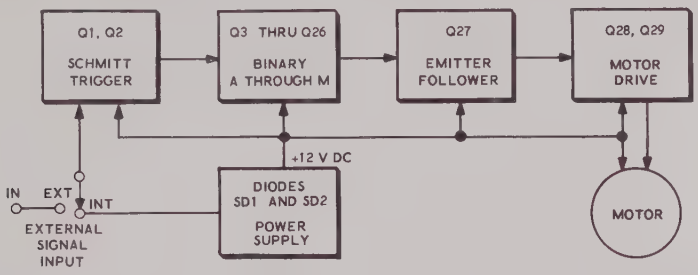


Figure 17

When Q28 conducts, it draw current through one-half of the motor winding and causes the motor to step, or turn. As Q28 cuts off and Q29 starts to conduct, the current flows through the other half of the motor winding and causes the motor to step again. Each time the signal polarity reverses, the motor steps and the chart paper moves .001667 inches. These chart movements are so small they cannot be seen as individual steps.

BINARY CIRCUITS

The Schematic shows binaries A and B in complete detail; and since all 12 binaries have identical circuits, binaries C through M are shown in block form.

One or more binaries are connected in the circuit by the Chart Speed switch to decrease the rate that the chart drive signal reverses polarity. This lower rate of polarity change, in turn, decreases the speed of the chart motor.

With the Chart Speed switch set at 10 SEC/IN, binary A is connected in the circuit and operates in the following manner: The square wave signal is coupled from the collector of transistor Q2, through capacitor C20, to the junction of diodes CD31 and CD40. Assume that transistor Q3 is cut off and Q4 is conducting until the square wave is applied to this circuit. When the square wave goes negative, Q3 starts conducting and Q4 is cut off. When the square wave goes positive, the operation of Q3 and Q4 does not change because diodes CD31 and CD40 will not pass a positive pulse. When the square wave goes negative again, Q4 starts to conduct and Q3 is cut off.

Since the operation of Q3 and Q4 reverses only when the square wave goes negative, the frequency of the output signal from binary A (at the collector of Q3) is one-half the frequency or rate of the square wave applied to the binary. The output signal of binary A is coupled from the collector of Q3, to lugs 11 and 14 of the Chart Speed switch. This signal is then coupled to emitter follower Q27, and to the motor drive circuit. The motor drive circuit in turn drives the chart motor. The motor speed has now been reduced to one-half it original speed by binary A.

When the Chart Speed switch is turned to 20 SEC/IN, binaries A and B are connected in the circuit. Binary A divides the signal frequency by 2 and binary B divides the signal frequency by 2 again. The original signal frequency coming from the Schmitt Trigger circuit is now divided by 4, which results in a chart speed that is one-fourth the original speed.

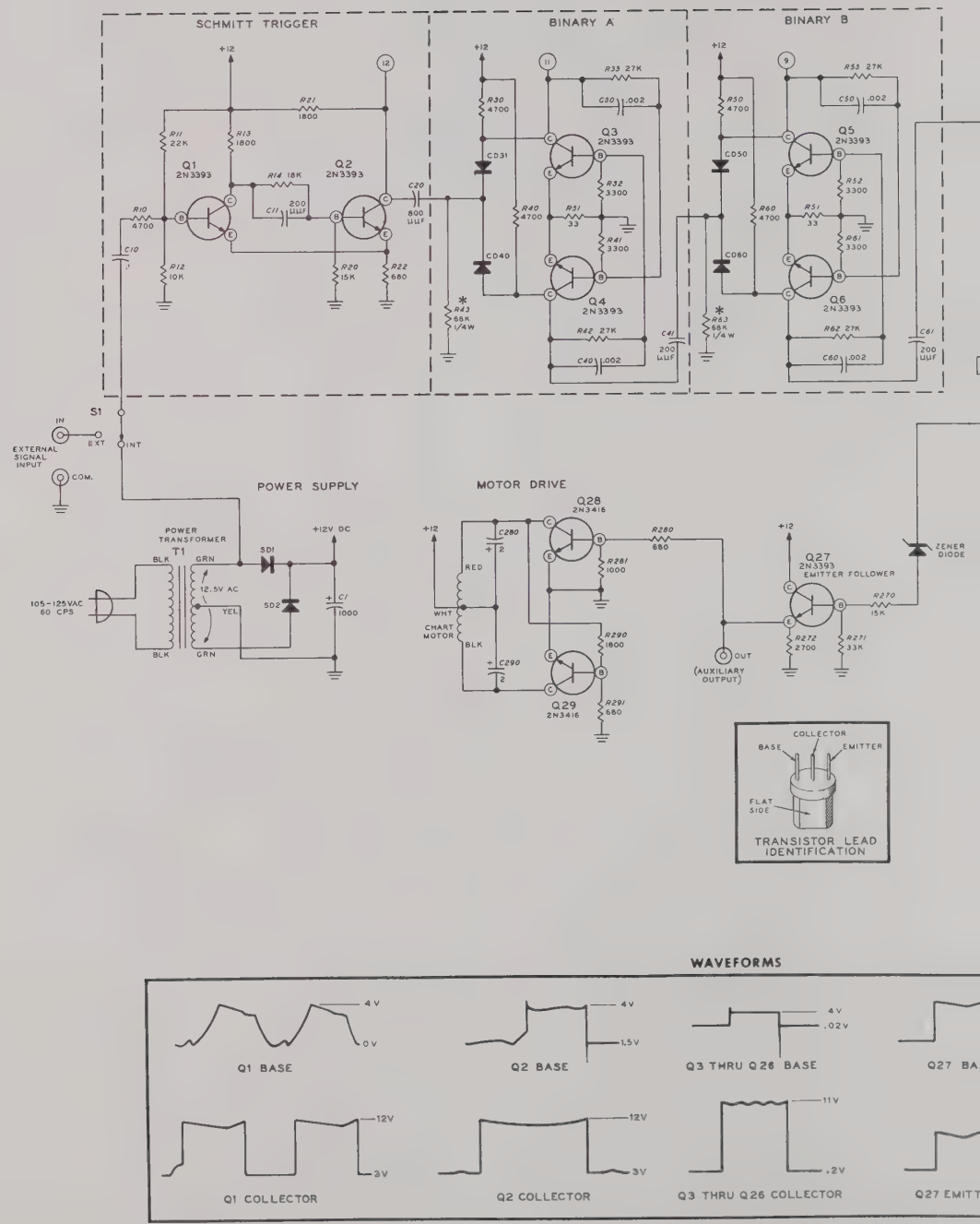
Figure 18 (fold-out from Page 18) shows the binary connections for the 21 positions of the Chart Speed switch. As explained above, each binary divides the signal frequency and chart speed by 2. When two binaries are used with a feedback diode (diodes CD1 through CD5) connected between them, the input signal frequency and the chart speed are divided by 3. Three binaries, with two feedback diodes, divide the signal frequency and the chart speed by 5.

AUXILIARY OUTPUT

The emitter of transistor Q27 is connected to the Auxiliary Output (OUT) jack so the chart drive signal can also be used to synchronize other events with this Chart Drive.

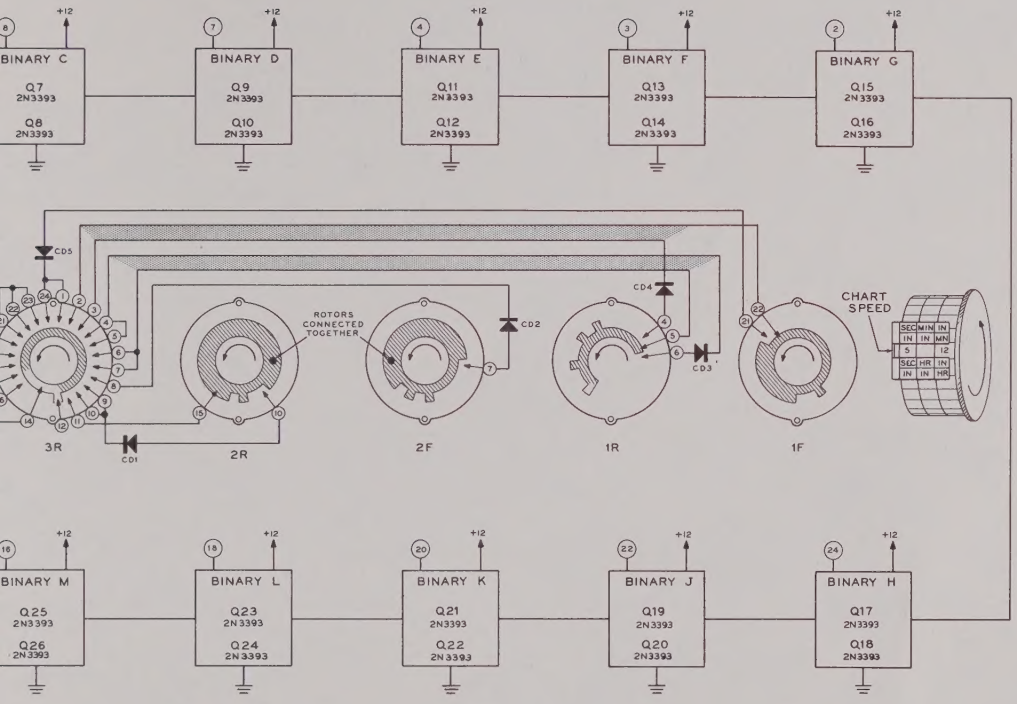
POWER SUPPLY

The transformer-operated power supply uses diodes SD1 and SD2 as a full-wave rectifier. Capacitor C1 removes AC ripple from the +12 V DC supply voltage before it is connected to the other circuits.


SCHMITT TRIGGER
BINARY A
BINARY B
+12
R21 1800
R11 22K
R13 1800
Q1 2N3393
Q2 2N3393
R14 18K
C11 200 µµF
R10 4700
C10
R12 10K
R20 15K
R22 680
C20 800 µµF
R30 4700
CD31
CD40
R40 4700
R31 33
R32 3300
R41 3300
Q3 2N3393
Q4 2N3393
R33 27K
C30 .002
R42 27K
C40 .002
R43 68K 1/4W
C41 200 µµF
R50 4700
CD50
CD60
R60 4700
R51 33
R52 3300
R61 3300
Q5 2N3393
Q6 2N3393
R53 27K
C50 .002
R62 27K
C60 .002
R63 68K 1/4W
C61 200 µµF
S1
IN
EXT
INT
EXTERNAL SIGNAL INPUT
COM.
POWER SUPPLY
POWER TRANSFORMER T1
BLK
GRN
12.5V AC
YEL
105-125VAC 60 CPS
SD1
SD2
+12V DC
+ C1 1000
MOTOR DRIVE
Q28 2N3416
C280
R280 680
R281 1000
RED
WHT
CHART MOTOR
BLK
C290
R290 1800
R291 680
Q29 2N3416
Q27 2N3393 EMITTER FOLLOWER
R270 15K
R272 2700
R271 33K
ZENER DIODE
OUT
(AUXILIARY OUTPUT)
COLLECTOR
BASE
EMITTER
FLAT SIDE
TRANSISTOR LEAD IDENTIFICATION

WAVEFORMS

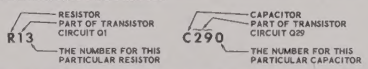
4 V
0 V
Q1 BASE
4 V
1.5 V
Q2 BASE
4 V
.02 V
Q3 THRU Q26 BASE
Q27 BA
12V
3V
Q1 COLLECTOR
12V
3V
Q2 COLLECTOR
11 V
.2V
Q3 THRU Q26 COLLECTOR
Q27 EMITT



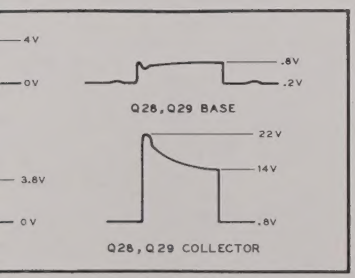
SCHEMATIC OF THE
HEATH
MULTI-SPEED CHART DRIVE
MODEL EUA-20-26

NOTES:

1. ALL RESISTORS ARE 1/2 WATT UNLESS MARKED OTHERWISE. RESISTOR VALUES ARE IN OHMS (K=1000).
2. ALL CAPACITOR VALUES ARE IN μfd UNLESS MARKED OTHERWISE.
3. * THIS RESISTOR IS ON BINARIES A, B, C, D, E, AND F ONLY.
4. WAVEFORMS TAKEN WITH A DC OSCILLOSCOPE FROM THE POINT INDICATED TO COMMON GROUND.
5. ⏚ THIS SYMBOL INDICATES COMMON GROUND THAT IS INSULATED FROM THE CHASSIS.
6. WAVEFORMS TAKEN WITH SWITCH S1 AT INT. AND CHART SPEED SWITCH FULLY CLOCKWISE.
7. CHART SPEED SWITCH SHOWN IN FULL CLOCKWISE POSITION AS VIEWED FROM THE KNOB END OF THE SHAFT.
8. ◯ THIS SYMBOL AROUND A NUMBER MEANS THAT THIS POINT IS CONNECTED TO THE LUG WITH THE SAME NUMBER ON WAFER 3R OF THE CHART SPEED SWITCH.
9. RESISTORS, CAPACITORS, AND DIODES ARE NUMBERED ACCORDING TO THE TRANSISTOR THEY ARE ASSOCIATED WITH. EXAMPLES:



10. BINARIES C THROUGH M ARE SHOWN IN BLOCK FORM. EACH OF THESE BINARIES HAS THE SAME CIRCUIT AS BINARY A.
11. REFER TO THE CIRCUIT BOARD X-RAY VIEW FOR THE PHYSICAL LOCATION OF THE PARTS ON THE CIRCUIT BOARD.



WARRANTY

The Heath Company warrants that its factory-wired products (except any batteries supplied therewith) shall be free of defects in materials and workmanship under normal conditions of use and service. The obligation of Heath under this warranty is limited to repairing or replacing any such factory-wired product upon verification that it is defective in this manner. This obligation is further limited to such defective products for which Heath is notified of the defect within a period of one year from the original date of shipment of the product.

The obligation of Heath under this warranty with respect to transportation expenses is limited to the cost of shipping the repaired or replacement product to the buyer, provided such repair or replacement comes within the terms of this warranty.

The foregoing warranty extends only to the original buyer and is expressly in lieu of all other warranties, expressed or implied. The foregoing warranty is further in lieu of all other obligations or liabilities on the part of Heath and in no event shall the Heath Company be liable for any anticipated profits, consequential damages, loss of time or other losses incurred by the buyer in connection with the purchase, operation or use of the product.

This warranty applies only to Heath products sold and shipped to points within the continental United States and to APO and FPO shipments. Warranty replacements for Heath products sold or shipped outside the United States is on an f.o.b. factory basis. Contact the Heath authorized distributor in your country or write: Heath Company, International Division, Benton Harbor, Michigan, U.S.A.

HEATH COMPANY

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